

Gibbs measures: definition, uses and abuses

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Stat mech à la Gibbs

Issue: to study systems with many components

Examples:

- ▶ *Particles in space*: Each particle characterized by a position and a velocity
- ▶ *Spins in a lattice* (pixels, particles): Each spin has a finite number of possible values

Stat mech approach:

- ▶ Look at finite “windows” (finite regions) Λ
- ▶ Replace detailed laws by a probabilistic description
- ▶ Find the asymptotic behavior for Λ huge

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Rough probabilistic prescription

Probability weights or densities

$$\frac{e^{-\beta H_\Lambda}}{Z_\Lambda}$$

where

- ▶ H_Λ = Hamiltonian; must be sum of local terms so that $H_{\tilde{\Lambda}} - H_\Lambda \sim |\tilde{\Lambda} \setminus \Lambda|$ for $\tilde{\Lambda} \subset \Lambda$
- ▶ β = inverse temperature (“coolness”)
- ▶ Z_Λ = partition function (normalization). Physics info:

$$\lim_{\Lambda} \frac{1}{|\Lambda|} \log Z_\Lambda = \text{pressure or free energy}$$

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Set up: Finite-spin lattice systems

- ▶ *Lattice* = Countable set \mathbb{L} (e.g. $\mathbb{L} = \mathbb{Z}^d$)
 - ▶ sites $x \in \mathbb{L}$
 - ▶ finite regions $\Lambda, \Gamma \Subset \mathbb{L}$
- ▶ *Single-spin space* S , here finite (e.g. Ising spins: $S = \{-1, 1\}$)
- ▶ *Configuration space* $\Omega = S^{\mathbb{L}}$ (A copy of S at each site)
 - ▶ Notation: $\Omega_{\Lambda} := S^{\Lambda}$
- ▶ *Configurations*: $\Omega \ni \omega = (\omega_x)_{x \in \mathbb{L}}$
 Notation:
 - ▶ $\Omega_{\Lambda} \ni \omega_{\Lambda} = (\omega_x)_{x \in \Lambda}$
 - ▶ $\omega_{\Lambda} \eta_{\Lambda^c} = \omega_{\Lambda} \eta$

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Basic kernels

Formally, finite window = finite region *of an infinite system*:

- ▶ Inside Λ : probability measure
- ▶ Outside Λ : fixed configuration (external condition)

That is, a family of probability measures

$$\pi(\cdot \mid \omega_{\Lambda^c})$$

or, more precisely, a kernel with two slots $\pi(\cdot \mid \cdot)$

This is a *probability kernel*

Need some formalization

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Measure-theoretical and topological set-up

Gibbsianness: interplay between topology and measure-theory

- ▶ S endowed with discrete topology and σ -algebra
- ▶ Ω endowed with the *product* topology and σ -algebra

In more detail:

- ▶ $\mathcal{F} = \sigma$ -algebra generated by the cylinders

$$C_{\sigma_\Lambda} = \{\omega \in \Omega : \omega_\Lambda = \sigma_\Lambda\}$$

- ▶ $\mathcal{F}_\Gamma = \sigma$ -algebra generated by cylinders with basis in $\Gamma \subset \mathbb{L}$

$$C_{\sigma_\Lambda}, \Lambda \subset \Gamma$$

- ▶ Topology also generated by the cylinders
 - ▶ cylinders are open
 - ▶ continuous functions are measurable

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Locality and continuity

f is a *local function* if

- ▶ It depends only on the spins on a *finite* region
- ▶ $\exists \Gamma \in \mathbb{L}$ such that $f(\omega) = f(\sigma)$ whenever $\omega_\Gamma = \sigma_\Gamma$
- ▶ $\exists \Gamma \in \mathbb{L}$ such that $(f \in \mathcal{F}_\Gamma)$

Properties:

- ▶ Local functions are continuous
- ▶ More generally: f is continuous iff, it is *quasilocal*

$$\sup_{\omega \in \Omega} \sup_{\sigma \in \Omega} \left| f(\omega_{\Lambda_n} \sigma) - f(\omega) \right| \xrightarrow{n \rightarrow \infty} 0$$

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Probability kernels

Definition

A **probability kernel** Ψ from a probability space (\mathcal{A}, Σ) to another probability space (\mathcal{A}', Σ') is a function

$$\Psi(\cdot | \cdot) : \Sigma' \times \mathcal{A} \longrightarrow [0, 1]$$

such that

- (i) $\Psi(\cdot | \omega)$ is a probability measure on (\mathcal{A}', Σ') for each $\omega \in \mathcal{A}$;
- (ii) $\Psi(A' | \cdot)$ is Σ -measurable for each $A' \in \Sigma'$.

Equilibrium systems in stat mech

System in $\Lambda \in \mathbb{L}$ described by a probability kernel

$$\pi_{\Lambda}(\cdot \mid \cdot) \text{ from } (\Omega, \mathcal{F}) \text{ to itself}$$

where

$$\pi_{\Lambda}(f \mid \omega) = \text{equilibrium value of } f \text{ when the configuration outside } \Lambda \text{ is } \omega$$

Operations with kernels

Composition of kernels

Ψ from (\mathcal{A}, Σ) to (\mathcal{A}', Σ') and Ψ' from $(\mathcal{A}'\Sigma')$ to $(\mathcal{A}'', \Sigma'')$,

$$(\Psi\Psi')(A''|\omega) = \int_{\mathcal{A}'} \Psi(d\omega'|\omega) \Psi'(A''|\omega')$$

Linear transformations of measures

$$\begin{aligned} \mathcal{P}(\mathcal{A}, \Sigma) &\longrightarrow \mathcal{P}(\mathcal{A}', \Sigma') \\ \mu &\longmapsto \mu' = \mu\Psi \end{aligned}$$

$$\mu'(A') = \int_{\mathcal{A}} \mu(d\omega) \Psi(A'|\omega)$$

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Equilibrium condition

System in $\Lambda \in \mathbb{L}$ described by a probability kernel $\pi_\Lambda(\cdot | \cdot)$

Equilibrium in Λ iff equilibrium in every box $\Lambda' \subset \Lambda$:

$$\pi_\Lambda(f | \omega) = \pi_\Lambda(\pi_{\Lambda'}(f | \cdot) | \omega) \quad (\Lambda' \subset \Lambda \in \mathbb{L})$$

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The notion of specification

Specification:

Family $\Pi = \{\pi_\Lambda : \Lambda \in \mathbb{L}\}$ of prob. kern. from (Ω, \mathcal{F}) to itself s.t.

- (i) $\pi_\Lambda(f | \cdot) \in \mathcal{F}_{\Lambda^c}$ for each $\Lambda \in \mathbb{L}$ and bounded measurable f
- (ii) Each π_Λ is *proper*: If $g \in \mathcal{F}_{\Lambda^c}$,

$$\pi_\Lambda(gf | \omega) = g(\omega) \pi_\Lambda(f | \omega)$$

for all $\omega \in \Omega$ and bounded measurable f

- (iii) The family Π is *consistent*:

$$\pi_\Lambda \pi_{\Lambda'} = \pi_\Lambda \quad \text{if } \Lambda' \subset \Lambda \in \mathbb{L}$$

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Consistent measures

Definition

μ on \mathcal{F} is **consistent** with a specification $\Pi = \{\pi_\Lambda : \Lambda \in \mathbb{L}\}$ if

$$\mu \pi_\Lambda = \mu \quad \text{for each } \Lambda \in \mathbb{L}$$

(DLR equations)

Remarks

- ▶ Several consistent measures = first-order phase transition
- ▶ specification \sim system of regular conditional probabilities
 - ▶ No apriori measure: conditions for *all* ω rather than a.s.
- ▶ Stat. mech.: conditional probabilities in search of measures

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Boltzmann prescription

Heuristically: $\pi_\Lambda \propto e^{-\beta H_\Lambda}$

- ▶ β *inverse temperature* (to be absorbed)
- ▶ H_Λ Hamiltonian = sum of local terms

Formally:

Interaction: family $\Phi = \{\phi_A \in \mathcal{F}_A : A \in \mathbb{L}\}$

Example: Ising interaction

$$\phi_A(\omega) = \begin{cases} -J_{\{x,y\}} \omega_x \omega_y & \text{if } A = \{x,y\} \text{ with } |x-y|=1 \\ -h_x \omega_x & \text{if } A = \{x\} \\ 0 & \text{otherwise} \end{cases}$$

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Gibbsian specifications

Hamiltonian for $\Lambda \in \mathbb{L}$ with frozen external condition ω

$$H_{\Lambda}^{\Phi}(\sigma_{\Lambda} \mid \omega_{\Lambda^c}) = \sum_{A \in \mathbb{L}: A \cap \Lambda \neq \emptyset} \phi_A(\sigma_{\Lambda} \omega)$$

Existence: Φ uniformly absolutely summable ($\Phi \in \mathcal{B}_1$) if

$$\sum_{A \ni x} \|\Phi_A\|_{\infty} < \infty \quad \text{for each } x \in \mathbb{L}.$$

Definition

The Gibbsian specification for $\Phi \in \mathcal{B}_1$ has kernels

$$\pi_{\Lambda}^{\Phi}(C_{\sigma_{\Lambda}} \mid \omega) = \frac{e^{-H_{\Lambda}^{\Phi}(\sigma_{\Lambda} \mid \omega_{\Lambda^c})}}{\text{Norm.}}$$

A Gibbs measure for Φ is a measure consistent with Π^{Φ}

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Gibbsianness and its properties

Definition

- ▶ Π is a **Gibbsian specification** if $\exists \Phi \in \mathcal{B}_1$ s.t. $\Pi = \Pi^\Phi$
- ▶ μ is a **Gibbs measure** if it is consistent with some Π^Φ

Gibbsian description (1968): *equilibrium* statistical mechanics

Exploited in other settings:

- ▶ Renormalized measures
- ▶ Spin-flip evolutions
- ▶ Particle systems
- ▶ Dynamical systems
- ▶ Quenched disordered systems.

Gibbsian description (1968): *equilibrium* statistical mechanics

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Gibbsianness

10⁶\$ question: How to tell whether a measure is Gibbsian?

Theorem (Kozlov)

A specification is Gibbsian if, and only if, it is both

(i) **Uniformly non-null:** for each $\Lambda \in \mathbb{L}$

$$\inf_{\sigma_\Lambda \in \Omega_\Lambda, \omega_{\Lambda^c} \in \Omega_{\Lambda^c}} \pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\Lambda^c}) =: c_\Lambda > 0$$

(ii) **Quasilocal (almost Markovian):** for each $\Lambda \in \Lambda$, $\sigma_\Lambda \in \Omega_\Lambda$

$$\sup_{\omega, \eta, \tilde{\eta} \in \Omega} \left| \pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\Lambda_n} \eta) - \pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\Lambda_n} \tilde{\eta}) \right| \xrightarrow{n \rightarrow \infty} 0$$

[C.f. Markovian:

$$\pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\partial_r \Lambda} \eta) - \pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\partial_r \Lambda} \tilde{\eta}) = 0]$$

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$$\sup_{\omega, \eta, \tilde{\eta} \in \Omega} \left| \pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\Lambda_n} \eta) - \pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\Lambda_n} \tilde{\eta}) \right| \xrightarrow{n \rightarrow \infty} 0$$

[C.f. Markovian:

$$\pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\partial_r \Lambda} \eta) - \pi_\Lambda(C_{\sigma_\Lambda} \mid \omega_{\partial_r \Lambda} \tilde{\eta}) = 0]$$

Comments

- ▶ Non-nullness = no forbidden configuration
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When is a measure non-quasilocal

Notation: $\mu_\Lambda(f | \omega) = E_\mu(f | \mathcal{F}_{\Lambda^c})(\omega)$

Key observations:

- ▶ μ is quasilocal if consistent with *no* quasilocal specification
- ▶ Need violation at a *single* $\hat{\omega}$ for a *single* μ_Λ for a *single* f
- ▶ Discontinuity must be *essential* (eg. for open neighbhds)

Recipe: Find

- ▶ Sequence of frozen regions Λ_{N_i}
- ▶ “Tilting” configurations η^\pm
- ▶ Larger annulus Λ_{R_i} to define open sets

Show that

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Non-Gibbsianness criterion:

μ not quasilocal if there exist

- ▶ a finite region Λ (often $|\Lambda| = 1$)
- ▶ a “special” configuration $\hat{\omega}$
- ▶ a (quasi)local function f
- ▶ a diverging sequence of regions $(\Lambda_{N_i})_{i \geq 1}$
- ▶ some $\delta > 0$ (independent of i)

such that for each $i \geq 1$ there exist

- (i) larger regions Λ_{R_i} , $R_i > N_i$
- (ii) two configurations η^+, η^- (possibly i -dependent), with

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Mechanism: Hidden variables

Quasilocality: frozen spins shield influence of distant regions

Non-quasilocality: info from afar even without fluctuations

Mechanism?

For transformed measures,

original variables act as “hidden-variables”

- ▶ Freezing transformed vbles = conditioning of original vbles
- ▶ These conditioned variables keep some freedom to fluctuate
- ▶ For particular ω the conditioned “hidden” system
 - ▶ exhibit a *phase transition*
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Linear stochastic transformations

A linear stochastic transformation is defined by

- ▶ An initial or *object* space $S^{\mathbb{L}}$
- ▶ A transformed or *image* space $S'^{\mathbb{L}'}$
- ▶ A kernel τ from $S^{\mathbb{L}}$ to $S'^{\mathbb{L}'}$ where

$$\tau(d\omega' | \omega) = \text{distribution of image spins when the initial spin configuration is } \omega$$

Particular cases:

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- ▶ **Renormalization transf.:** Image = renormalized

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Block renormalization transformations

Definition: Kernel from $S^{\mathbb{L}}$ to $(S')^{\mathbb{L}'}$ of the form

$$\tau(d\omega' | \omega) = \prod_{x' \in \mathbb{L}'} \tau_{x'}(d\omega'_{x'} | \omega_{B_{x'}})$$

Main examples: $\mathbb{L}' = \mathbb{L}$, $B_{x'} = \Lambda_{b-1} + bx'$

Particular case: **Deterministic transformations**

$$\tau_{x'}(\cdot | \omega_{B_{x'}}) = \delta_{T_{x'}(\omega_{B_{x'}})}(\cdot)$$

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Deterministic block RT

- ▶ *Decimation*: $S = S'$

$$\tau_{x'}(\cdot \mid \omega_{B_{x'}}) = \delta_{\omega_{bx'}}$$

- ▶ *Spin contractions*: $S' \subsetneq S$, $B_{x'} = \{x'\}$

- ▶ *Sign fields*: $S \subset \mathbb{R}$ symmetric,

$$T_{x'}(\omega_{x'}) = \text{sign}(\omega_{x'})$$

- ▶ “Fuzzy” spins: $S = \cup_{i \in I} S_i$ (partition), $S' = I$

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Renormalization transformations

- ▶ *Block average:* $S' \supset S$
 \neq

$$T_{x'}(\omega_{B_{x'}}) = \frac{1}{|B_{x'}|} \sum_{y \in B_{x'}} \omega_y$$

- ▶ *Majority rule:* $S' = S = \{-1, 1\}$

$$T_{x'}(\omega_{B_{x'}}) = \text{sign} \left[\sum_{y \in B_{x'}} \omega_y \right]$$

Stochastic block RT

- ▶ *Majority with even block*: stochastic decision if

$$\sum_{y \in B_{x'}} \omega_y = 0$$

- ▶ *p-Kadanoff transformation*: $S = S'$

$$\tau_{x'}(d\omega'_{x'} \mid \omega_{B_{x'}}) = \frac{\exp\left[p \omega'_{x'} \sum_{y \in B_{x'}} \omega_y\right]}{\text{Norm.}} d\omega_{B_{x'}}$$

The question

Physicists: RT at Hamiltonian level

$$\begin{array}{ccc}
 \mu & \xrightarrow{\tau} & \mu' \\
 \uparrow & & \downarrow \\
 \Phi & \xrightarrow{\mathcal{R}} & \Phi'
 \end{array}$$

Success led to applications to 1st-order phase transitions. Then,

$$\begin{array}{ccc}
 \{\mu_1, \dots\} & \begin{array}{c} \rightrightarrows \\ \rightleftarrows \\ \rightleftarrows \end{array} & \{\mu'_1, \dots\} \\
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The renormalization issue

The answer

In fact,

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Israel: 2×2 -decimation of the Ising model

- ▶ $\hat{\omega}'_{x'} = (-1)^{|x'|} =$ decorated Ising model on *internal* spins
- ▶ Model equivalent to an Ising model at a higher temperature
- ▶ $\eta'_{x'}^{\pm} = \pm 1$ in an annulus chooses the “ \pm ”-phase

Thus,

$$\mu' \left(\sigma'_0 \mid \hat{\omega}'_{\Lambda'_R} (+1)_{\Lambda'_{R+1} \setminus \Lambda'_R} \sigma'^+ \right) - \mu' \left(\sigma'_0 \mid \hat{\omega}'_{\Lambda'_R} (-1)_{\Lambda'_{R+1} \setminus \Lambda'_R} \sigma'^- \right)$$

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General case

Specification with densities proportional to

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The image ω' acts as “fields” on the original $\sigma_{\Lambda} \omega$

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In this way, all usual transformations lead to non-Gibbsianness (even outside the coexistence region)

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Unquenching

Non-Gibbsianness in spin-flip evolutions

Simulations: spin-flip dynamics converging to a target measure
(Metropolis, heath-bath, Glauber)

Often: ordered initial configuration

“Unquenching”: high- T dynamics applied a low- T Gibbs state

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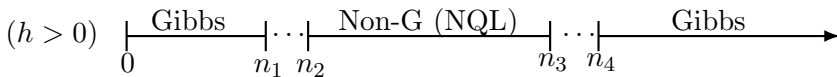
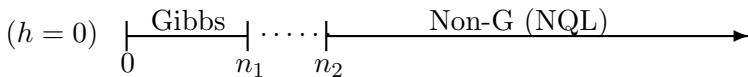
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Results for parallel independent updating



Interpretation: The key questions

Which is the most probable history of an improbable configuration?

Is the (atypical) droplet $\hat{\omega}'_{\Lambda}$

- ▶ *Nurture*: created by the dynamics?
- ▶ *Nature*: created initially and survived?

The history of $\hat{\omega}'_{\Lambda}$

- ▶ is it uniquely defined by the final configuration?
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Interpretation: Tentative answers:

Short times:

- ▶ Only a few changes possible
- ▶ Everybody nature
- ▶ Only one possible history

Not-too-short times:

- ▶ System relaxes first and forms $\hat{\omega}'_{\Lambda}$ at the last moment
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- ▶ Possibility of multiple histories:
 - ▶ Histories start from typical configurations of different phases
 - ▶ Same volume cost, different boundary cost
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Non-Gibbsianness as discontinuity

Conclusion:

Non-Gibbsianness = history with discontinuous dependence on the surrounding configuration

Scenario:

- ▶ Single history = Gibbsianness
- ▶ Multiple histories can lead to non-Gibbsianness:

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Wake-up calls for non-Gibbsianness

Griffiths and Pearce (1978): *peculiarities* in Renormalized measures

Israel (1979): peculiarity=absence of *quasilocality*

Other examples (1987–9):

- ▶ Spin contractions (Lebowitz-Maes, Dorlas-van Enter)
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